Alain Goriely

The Mathematics and Mechanics of Biological Growth



Alain Goriely Department of Mathematics University of Oxford Oxford UK

ISSN 0939-6047 ISSN 2196-9973 (electronic) Interdisciplinary Applied Mathematics ISBN 978-0-387-87709-9 ISBN 978-0-387-87710-5 (eBook) DOI 10.1007/978-0-387-87710-5

Library of Congress Control Number: 2016963741

Mathematics Subject Classification (2010): 74L15, 74B20, 92C10, 92Bxx, 92C30, 92C50, 92C80

© Springer Science+Business Media LLC 2017

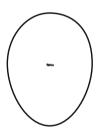
This work is subject to copyright. All rights are reserved by the Publisher, whether the whole or part of the material is concerned, specifically the rights of translation, reprinting, reuse of illustrations, recitation, broadcasting, reproduction on microfilms or in any other physical way, and transmission or information storage and retrieval, electronic adaptation, computer software, or by similar or dissimilar methodology now known or hereafter developed.

The use of general descriptive names, registered names, trademarks, service marks, etc. in this publication does not imply, even in the absence of a specific statement, that such names are exempt from the relevant protective laws and regulations and therefore free for general use.

The publisher, the authors and the editors are safe to assume that the advice and information in this book are believed to be true and accurate at the date of publication. Neither the publisher nor the authors or the editors give a warranty, express or implied, with respect to the material contained herein or for any errors or omissions that may have been made. The publisher remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

Printed on acid-free paper

This Springer imprint is published by Springer Nature
The registered company is Springer Science+Business Media LLC
The registered company address is: 233 Spring Street, New York, NY 10013, U.S.A.



This book is dedicated to the 3Z:

Zébulon, Zakkai, and Zéphyr.

Not as an acknowledgement of their patience or help, as they have none and gave me little, but for the daily joy and chaos that they create and for the fabulous examples of growth processes that they generated over the last seventeen years. My interest in growth conveniently coincided with their birth and childhood.

Preface



To the nature lover, there is a distinct feeling of awe and beauty when observing the gradual development of a child, the slow growth of trees, the fine structure of a seashell, or the opening of a flower. Throughout human cultures and civilizations, philosophers, artists, and scientists have marveled and pondered at the cycle of life, the changes from an embryonic form to a newborn, the maturation of the newborn, and the constant physiological renewal of the adult. All these processes can be summarized by a single concept: growth. Growth provides an organism with the ability to adapt and control its environment through its life and through time. Growth is at the very core definition of life itself.

The problem of growth has been traditionally central to all aspects of biological research but of marginal interest to physicists, engineers, and mathematicians. However, in the last thirty years with the rise of medical bioengineering, biophysics, and mathematical biology, the problematic of describing and understanding growth quantitatively has become a main topic of multidisciplinary research.

Writing a book in an active field, spanning centuries of knowledge and covering multiple disciplines, is a risky proposition. The idea for this monograph came to me more than ten years ago when I realized that the general topics of mathematics of growth was becoming a central theme of research for many scientists in different communities. There was a clear need to bridge different concepts and ideas originating from multiple communities and, in particular, create a common language to

x Preface

describe phenomena appearing in different scientific disciplines. This monograph is an attempt in this direction.

Following my own interests and limited abilities, there is a strong bias in the choice of topics presented in this monograph.

First, most of the descriptions are at the continuum level, essentially from tissues to organs with very little discussion on cellular processes responsible for growth. Whereas much is known at the cellular level, our understanding of transduction mechanisms, linking cellular processes to tissue and organ growth, is still in infancy.

Second, the emphasis is on physical and mechanical aspects of growth at the level of organs and organisms but not at the population level. The mathematics of evolving populations of cells or individuals, and their coupling with chemical fields is well developed. It can be found in classic textbooks of mathematical biology and will not be repeated here.

Third, the theory is developed around modern concepts of solid mechanics and illustrated through the use of reduced simplified models that can be analyzed by the methods of applied mathematics. Unavoidably, the concepts may be advanced but the models are often simple. The hope is that these models provide some insight into the mechanisms governing growth and the interplay between growth, mechanics, and geometry. More realistic models would typically require both an extensive discussion of the underlying biological system and extensive computational analyses. I leave these tasks to the experts in these different fields.

Fourth, the emphasis is on the consequences of growth rather than on its origin. The discussion is mostly restricted to the analysis of tissue and organs made out of a single elastic component rather than the more general theory of mixtures that takes into account the coupling between fluids and various tissue components. These advanced theories for growth and remodeling have been used to develop realistic models but cannot be easily analyzed mathematically. They also require a more general computational framework that is still in development. My general philosophy is that little progress can be made for models with multiple components unless we have a thorough understanding of the simpler problems studied here.

Fifth, whereas I try to provide general introductions to different topics and key references to many authors, most of the topics presented here have come about through my own research projects. I have worked on these with various collaborators over the last twenty years. Therefore, this monograph is not an exhaustive review of the field as much as my personal views on the subject. I do not believe that it is the only approach or even that it is superior to other points of view. I would like to encourage other researchers to provide alternative, complementary, or contradictory approaches as it will only enrich the debate and help develop a general theory of growth. While I have tried to be thorough in citing relevant works in the literature, I have undoubtedly missed important references and, I can only apologize to the colleagues that I have offended in the process.

This book is designed to be at the quadruple interface of mathematics, biology, physics, and mechanics. Life at the interface is particularly rich and exciting as it takes advantage of ideas, concepts, and methods from different fields. It is also

Preface xi

particularly dangerous as it is the ideal ecological zone for highly specialized predators. I expect that biologists will find the biological modeling over-simplistic and focussing on questions of little interest to them. I believe that many mathematicians will find the mathematical description too informal and lacking the rigor expected in various well-established disciplines ranging from partial differential equations to differential geometry. Some engineers may lament at the lack of finite-element simulations and detailed mechanical measurements. And, I fully expect that many physicists will view the treatment of mechanics as being too technical and unnecessarily complicated. These criticisms are all valid. It is the curse of interdisciplinarity to always fall short of the expectations required by disciplinary purity. But, it is only when these opprobriums will be bestowed on me that I will know that I have managed to reach different communities and that I may have attained some measure of success.

A Reader's Map

This book was conceived to be read at different levels, depending on the reader's interests and background. The difficulty is that a mathematical and mechanical theory of growth naturally combines aspects of biology, mathematics, and mechanics. The bio-mechanician with a good grip of solid mechanics may not always be familiar with some methods of applied mathematics. Similarly, many applied mathematicians and physicists, while often well trained in fluid mechanics, are not typically exposed to advanced concepts of solid mechanics. For the biologically trained but mathematically inclined readers, mathematics and mechanics may be appealing but may present technical difficulties. Accordingly, topics are presented in order of conceptual and mathematical difficulties.

Inspired by the structure of the excellent textbook "Nonlinear Dynamics and Chaos" by Steven Strogatz, I organized this monograph according to the dimensionality of the problem, starting in dimension one before considering problems in dimension two and only then presenting the general theory in three dimensions. Indeed, the coupling of growth and mechanics can be illustrated in simplified geometries where the fundamental concepts can be easily understood. Once these concepts are understood, they are progressively generalized.

Part I presents a general introduction to growth, hopefully accessible to all readers. It presents basic aspects and classification of growth processes and, more or less, use historical developments and abundant examples from biology and physiology to introduce key concepts relating biological growth to physical cues.

Part II was specifically developed for this monograph, both to introduce basic mechanical ideas such as elasticity, viscoelasticity, and plasticity; but also to illustrate the interplay between growth processes and mechanics. In the first chapter, I discuss the simplest instances of growth by restricting deformations along a line. In the process of writing this book, I realized that there was no general theory of growth for filamentary structures. With Derek Moulton and Thomas Lessinnes,

xii Preface

we filled this gap and showed how to generalize the theory of elastic rods to include the effects of growth and remodeling. These ideas are used to model many interesting systems, mostly taken from the world of plants.

Part III further generalizes these concepts in simple two-dimensional geometries with applications to accretive growth problems such as seashells and microbial systems exhibiting tip growth. Most of the discussion of two-dimensional elastic surfaces is restricted to axisymmetric membranes and shells. The general problem of deriving a general theory of morphoelastic shells would require a few more chapters and only a short introduction to the general problem is given.

Part IV presents a general theory of growth for three-dimensional bodies based on the twin concept of evolving reference configuration and the multiplicative decomposition of the deformation gradient. This part starts with a brief description of the classic theory of nonlinear elasticity so that readers not versed in the language of large deformations mechanics can learn the basic tools. An extensive discussion on the kinematics of growth viewed as evolving configurations is presented. It is followed by a general discussion on growth laws, dynamics, and stability. The two last chapters are devoted to detailed examples and applications in spherical and cylindrical geometries.

Rather than providing a final conclusion to a field that is still blooming, I conclude, in Part V, with a list of ten challenges. It is my hope that these challenges will motivate other researchers and help move the field forward.

Oxford, UK 2016 Alain Goriely

Acknowledgements

I am deeply indebted to a number of friends and collaborators. First, it is with great pleasure that I acknowledge the influence of Michael Tabor on both my professional and intellectual life. Twenty years ago, tired of playing with problems in the theory of integrability, Michael and I decided to look at problems related to growth and mechanics. At that time, we knew next to nothing about rods, membranes, nonlinear elasticity or growth. All we had were a few questions that we thought deserved to be investigated and a few methods from applied mathematics that people did not seem to be using in mechanics. We taught each other the basics and tried to model simple systems, inching our way to a better understanding. Many of the basic ideas and applications presented in this book were born out of these discussions.

Another major influence on this work was my collaboration with Martine Ben Amar. During a sabbatical in Paris, we learned the foundations of rational mechanics and developed together the theory of growth-induced instabilities for nonlinear elastic systems. It was an exciting time of scientific discovery and it remains one of the best academic years of my life.

I would also like to acknowledge the many striking contributions of Derek Moulton through our years of collaboration. In his own work, Derek has been exploring the consequences of growth in many different settings and, doing so, has systematically propelled the field forward. We have been partners in crime for many years, shared the meager rewards of our malfeasance, and paid the price for our idiosyncratic interests. I hope that his punishment will be lighter than mine.

Many of the ideas discussed in this monograph are also the product of many years of work, discussions, reflection, and meetings with my collaborators. In particular, I have tremendously benefited from my interactions with Jon Chapman, Régis Chirat, Michel Destrade, Marcelo Epstein, Krishna Garikipati, Ray Goldstein, Andrew Hausrath, Ellen Kuhl, Thomas Lessinnes, John Maddocks, Angela Mihai, Sébastien Neukirch, Giuseppe Saccomandi, Dominic Vella, Sarah Waters, John Wettlaufer, and Arash Yavari. I take this opportunity to let them know that their intellect and friendship are precious to me.

xiv Acknowledgements

Central to all academic endeavors is the training and interactions with students. I have been very lucky to be able to supervise several bright students whose hard work features prominently here: Alexandre Erlich, Georgina Lang, Tyler McMillen, Andrey Melnik, Joe McMahon, and Rebecca Vandiver.

It is with great pleasure that I acknowledge the courage of many helpful readers to climb mountains of typos, to dig into incoherent statements, to sort out inconsistent notations, and to uncover logical flaws. In particular, I am indebted to: Nita Goriely, James Kwiecinski, Angela Mihai, Oliver O'Reilly, Thomas Woolley, and I am especially grateful to Nicola Kirkham for her outstanding work and to Achi Dosanjh and Nick Valente at Springer for their patience and support. Their feedback and help are gratefully acknowledged and, obviously, the remaining mistakes are all mine.

Finally, none of it would have happened without the constant help of my wife, Nita. I will say no more, as the rest is between the two of us.

Contents

3.1.2

Pai	rt I Ir	ntroductio	on: Where It All Starts	
1	Basic	Aspects	of Growth	3
	1.1	Classific	cation	4
		1.1.1	Tip Growth	5
		1.1.2	Accretive Growth	7
		1.1.3	Volumetric Growth	9
	1.2	The Sca	aling of Growth	10
	1.3		e Growth	17
	1.4	The Kir	nematics of Growth	23
2	Mech	anics and	Growth	27
	2.1		is Influenced by Stress	27
		2.1.1	The Growth of Stems	30
		2.1.2	The Growth of Axons	30
		2.1.3	Thoma's Law for Arteries	32
		2.1.4	Woods' Law for the Heart	32
		2.1.5	Wolff's Law for Bones	34
		2.1.6	Davis' Law for Soft Tissues	36
		2.1.7	Tumor Spheroid Growth	38
	2.2	Stress is	s Influenced by Growth	38
		2.2.1	Tissue Tension in Plants	40
		2.2.2	Residual Stress in Physiology	43
	2.3	The The	eory of Morphoelasticity	45
	2.4	A Short	t History of Growth Modeling	46
	2.5	A Revie	ew of Reviews	49
3	Discr	ete Comp	outational Models	51
	3.1	_	ice Models	51
		3.1.1	Cellular Automata	51

52

xvi Contents

	3.2	Off-Latti	ce Models	54
		3.2.1	Center Dynamics Models	54
		3.2.2	Vertex Dynamics Models	56
		3.2.3	Advantages and Drawbacks	58
Part	t II Fi	ilament G	Frowth: A One-Dimensional Theory	
4	Growi	ng on a I	Line	63
	4.1		e: A Growing Rod in One Dimension	66
	4.2	Purely E	Elastic Deformations	67
	4.3	Growth	Without Elastic Deformations	69
		4.3.1	Example: Tip Growth	69
		4.3.2	Application: Spheroid Tumor Growth	71
	4.4	Growth	with Elastic Deformation	76
		4.4.1	Growth of a Rod Between Two Plates	76
		4.4.2	Three Different Configurations	77
		4.4.3	Homeostatic Growth	78
		4.4.4	Application: The Growth of Neurons	80
		4.4.5	Is This Just Plasticity?	85
	4.5	Applicat	ion: The Growth of Plant Cells	88
		4.5.1	Lockhart Model	89
		4.5.2	Extending Lockhart's Model	92
5	Elastic	Rods		97
	5.1	The Kin	ematics of Curves and Rods	98
		5.1.1	Curves and Frenet Frames	98
		5.1.2	Rods and General Frames	99
		5.1.3	Inextensible, Unshearable Rods	102
	5.2	The Med	chanics of Elastic Rods	103
		5.2.1	Balance of Linear Momentum	104
		5.2.2	Balance of Angular Momentum	106
		5.2.3	Local Mechanics of Rods	107
	5.3	Constitu	tive Laws for Elastic Rods	108
		5.3.1	Extensible and Shearable Elastic Rods	108
		5.3.2	Inextensible and Unshearable Rods	108
		5.3.3	Isotropic, Extensible, but Unshearable Rods	110
	5.4	Scaling		110
	5.5		and Torsional Stiffnesses	111
	5.6	_	chhoff Elastic Rod Model: A Summary	113
	5.7		: Helical Rods	116
		5.7.1	Geometry of Helices	116
		5.7.2	Helical Equilibria	117
		5.7.3	Overwinding or Underwinding Helices	119

Contents xvii

	5.8	The Pla	anar Elastica: Bernoulli–Euler Equations	122
		5.8.1	Static Solutions	122
6	Morn	hoelastic	Rods	125
•	6.1		atics of a Growing Rod	127
	6.2		nics of a Growing Rod	128
	6.3		on Laws for Growing Rods	129
	6.4		le: The Remodeling of Stems	130
	6.5		kling Criterion	132
		6.5.1	Example: Michell's Instability	133
		6.5.2	A General Perturbation Expansion	136
		6.5.3	Bifurcation Criterion for Elastic Buckling	138
		6.5.4	Example: The Growing Ring	138
		6.5.5	A Growing Ring with Remodeling	140
	6.6		ng Rods on a Rigid Foundation	142
		6.6.1	Example: A Growing Ring on a Foundation	143
		6.6.2	Example: A Straight Rod Growing	
			on a Foundation	145
	6.7	Applica	ation: Growing Vines	149
		6.7.1	Perversion in Tendrils	149
		6.7.2	Twining Vines	162
		6.7.3	Application: The Growth of Bacillus subtilis	168
Pai	t III	Surface (Growth: A Two-Dimensional Theory	
7	Accre	etive Gro	wth	175
	7.1		c Accretive Growth	176
		7.1.1	Simple Examples	179
		7.1.2	Shape Planarity	184
		7.1.3	Shape Invariance	185
		7.1.4	Self-Similarity	187
	7.2	Applica	ation: The Growth of Seashells	187
		7.2.1	Background	187
		7.2.2	Geometric Description	189
		7.2.3	Accretive Growth of Seashells	193
		7.2.4	Other Accreted Structures	194
		7.2.5	The Role of Mechanics in Morphological	
			Patterns	196
8	Mem	branes aı	nd Shells	207
	8.1	Elastic	Membranes	208
		8.1.1	Kinematics	208
		8.1.2	Mechanics	211

xviii Contents

		8.1.3	Constitutive Laws	214
		8.1.4	A Complete Set of Equations	214
		8.1.5	Application: The Shape of Sea Urchins	216
	8.2	Nonline	arly Elastic Shells	220
		8.2.1	Mechanics	220
		8.2.2	Scalings	223
		8.2.3	Application: The Rice Blast Fungus	224
9	Growi	ng Mem	branes	231
	9.1		elastic Membranes	232
	9.2	-	tion: Microbial Tip Growth	234
		9.2.1	Background	234
		9.2.2	Bacterial Filaments: Actinomycetes	234
		9.2.3	Fungi	237
		9.2.4	Root Hairs	238
		9.2.5	Modeling of Tip Growth	239
		9.2.6	A Model for Hyphal Growth	240
		9.2.7	Tip Shapes for Filamentous Bacteria	241
		9.2.8	Lysis and Beading	
		9.2.9	Shear Stress and the Normal Growth Hypothesis	247
10	Morni	noelastic	Plates	251
	10.1		Plates	252
	10.1	10.1.1	Mean and Gaussian Curvatures	252
		10.1.2	Growing Elastic Plates	254
		10.1.2	Clowing Linear Linear Control of the	-0.
Par	t IV	olumetr	ic Growth: A Three-Dimensional Theory	
11	Nonlin	near Elas	ticity	261
	11.1		tics	262
		11.1.1	Scalars, Vectors, and Tensors	264
		11.1.2	Spatial Derivatives of Tensors	266
		11.1.3	Derivatives in Curvilinear Coordinates	268
		11.1.4	Derivatives of Scalar Functions of Tensors	270
		11.1.5	The Deformation Gradient	272
		11.1.6	Volume, Surface, and Line Elements	274
		11.1.7	Polar Decomposition Theorem	276
		11.1.8	Velocity, Acceleration, and Velocity Gradient	277
	11.2	Balance	Laws	278
		11.2.1	Balance of Mass	279
		11.2.2	Balance of Linear Momentum	280
		11.2.3	Balance of Angular Momentum	282
		11.2.4	Many Stress Tensors	283
		11.2.5	Balance of Energy for Elastic Materials	284

Contents xix

	11.3	Constitutive Equations for Hyperelastic Materials	285	
		11.3.1 Internal Material Constraints	286	
	11.4	Summary of Equations	287	
	11.5	Boundary Conditions	288	
	11.6	Objectivity and Material Symmetry		
	11.7	Isotropic Materials	289	
		11.7.1 Adscititious Inequalities	291	
		11.7.2 Choice of Strain-Energy Functions	293	
	11.8	Examples	296	
		11.8.1 A Simple Homogeneous Deformation	296	
		11.8.2 The Half-Plane in Compression	298	
		11.8.3 The Inflation–Extension of a Tube	299	
	11.9	Universal Deformations for Isotropic Materials	305	
	11.10	Bifurcation, Buckling, and Instability	310	
		11.10.1 Example: Bifurcation of the Half-Plane	314	
	11.11	Anisotropic Materials	320	
		11.11.1 One Fiber	322	
		11.11.2 Two Fibers	323	
		11.11.3 Example: The Fiber-Reinforced Cuboid	324	
		11.11.4 Example: The Fiber-Reinforced Cylinder	328	
		11.11.5 Application: The Hydrostatic Skeleton	336	
		11.11.6 Fiber Dispersion	339	
12	The K	inematics of Growth	345	
	12.1	A Thought Experiment	346	
	12.2	Relieving Stresses	348	
	12.3	The Conceptual Hypothesis of Morphoelasticity	353	
	12.4	Example: The Growing Ring	355	
	12.5	The Problem of Incompatibility	358	
	12.0	12.5.1 A Differential Geometry Perspective	359	
		12.5.2 An Analytic Perspective	371	
		• •		
13		ce Laws.	375	
	13.1	The Slow-Growth Assumption	376	
	13.2	Balance of Mass	377	
	13.3	Balance of Linear and Angular Momenta	380	
	13.4	Energy Balance	381	
	13.5	Imbalance of Entropy	382	
	13.6	Elastic Constitutive Laws	383	
	13.7	Summary of Volumetric Morphoelasticity	384	
	13.8	Simple Examples	385	
		13.8.1 A Growing Cuboid	385	
		13.8.2 Two Growing Cuboids	386	
		13.8.3 A Growing Ring	388	

xx Contents

	13.9	Mixture Models	392	
		13.9.1 Classical Mixture Theory	393	
		13.9.2 Constrained Mixture Theory	396	
14	Evolu	tion Laws and Stability	399	
	14.1	Symmetry of the Growth Tensor	400	
	14.2	Isotropic Growth and Gel Swelling	403	
	14.3	Discrete Growth Steps	404	
	14.4	The Thermodynamics Perspective	405	
	14.5	Phenomenological Laws and Homeostatic Stress	408	
	14.6	Dynamics of Homogeneous Deformations	410	
		14.6.1 Diagonal Deformations	411	
		14.6.2 A Two-Dimensional Example	415	
	14.7	Remodeling	419	
		14.7.1 Fiber Remodeling of a Cuboid in Tension	421	
	14.8	Growth Induced Instability	425	
15	Growi	ing Spheres	431	
	15.1	The Growing Shell	431	
		15.1.1 Kinematics of Growing Spheres	432	
		15.1.2 Stresses in a Growing Sphere	435	
	15.2	Examples	437	
		15.2.1 Anisotropic Growth	437	
		15.2.2 Differential Growth	438	
	15.3	Limit-point Instability and Inflation Jump	442	
		15.3.1 The Effect of Growth on the		
		Limit-point Instability	448	
	15.4	Singularities in Growing Solid Spheres		
	15.5 Cavitation		450	
		15.5.1 Cavitation Induced by Tensile Loading	452	
		15.5.2 Cavitation Induced by Growth	452	
	15.6	Instability Due to Anisotropic Growth	453	
		15.6.1 A Numerical Scheme	460	
		15.6.2 Thin-Shell Limit	462	
		15.6.3 Thick-Shell Limit	465	
		15.6.4 Bifurcation of the Growing Shell	467	
	15.7	Instability Due to Differential Growth	470	
		15.7.1 Instability in a Shrinking Shell	471	
		15.7.2 Instability of a Shell Growing Inside a Medium	473	
16	Growi	ing Cylinders	475	
	16.1	Kinematics of the Growing Cylinder	476	
	16.2	Application: Cavitation in Plants	480	
		16.2.1 Background	480	
		16.2.2 The Model	483	

Contents xxi

		16.2.3	Analysis	484
		16.2.4	Discussion	484
	16.3	Bifurcati	ion of Growing Cylinders	487
		16.3.1	Buckling Versus Barreling	487
		16.3.2	Bifurcation and Buckling in Growing Cylinders	493
		16.3.3	The Effective Rigidity of a Growing Cylinder	496
		16.3.4	An Example	498
	16.4	Applicat	ion: Tissue Tension in Plants	499
		16.4.1	Background	499
		16.4.2	The Model	501
		16.4.3	Analysis	503
		16.4.4	Discussion	507
	16.5	Applicat	ion: The Buckling of Arteries	509
		16.5.1	Background	509
		16.5.2	The Model	512
		16.5.3	Analysis	518
		16.5.4	Discussion	523
	16.6	Circumf	erential Buckling and Mucosal Folding	524
		16.6.1	Example: Circumferential Buckling	
			in a Cylinder	526
		16.6.2	Example: A Two-Layer Cylinder	528
	16.7	Applicat	ion: Asthma and Airway Remodeling	530
		16.7.1	Background	530
		16.7.2	The Model	532
		16.7.3	Analysis	534
		16.7.4	Discussion	538
	16.8	Residual	Stress Through Fiber Contraction	539
		16.8.1	Rotation of a Pressurized Anisotropic Cylinder	540
	16.9	Applicat	ion: The Spiral Growth of Phycomyces	542
		16.9.1	Background	542
		16.9.2	The Model	544
		16.9.3	Analysis	546
		16.9.4	Discussion	551
Par	t V C	onclusion	: Where It Does Not End	
17	Ten C	hallenges		555
	17.1		eology of Growth	555
	17.2		gulation of Growth and Growth Size	557
	17.3	-	sive Growth Law	559
	17.4		lle: From Discrete to Continuous and Back	561
	17.5		Versus Diffusion	564
	17.6		ysics: Coupling Growth with Other Fields	567
	17.7		ry of Accretive Growth	570
			•	

xxii Contents

17.8	Dynamics and Post-bifurcation Behavior	572
17.9	Active Forces, Actives Stresses, and Active Strains	574
17.10	The Mathematical Foundations	578
References		
Index		637